PREPARED BY:

MFWG

SUPERCEDING DATE: 24 NOV B6

SYSTEM: MECHANICAL ARM SUBSYSTEM ASS'Y P/H: 51140J1585 PRUTTER: SRMS ASS' NOMENCLATURE: MECHANICAL ARM HAME, OTY, & DRAWING REF. FMEA **FHEA** FAILURE MODE HDWR / FUNC. **FAILURE EFFECT** RATIONALE FOR ACCEPTANCE REF. REV. AND 2/TRA CAUSE DESIGNATION END ITEM CRITICALITY SCREENS: A-FAIL, B-PASS, C-PASS 4040 3 OPTICAL MODE: THE POSTION DESIGN FEATURES POSITION ERRONEOUS INFORMATION TO ANGLE COMPUTER 15 ENCODER 011-5 P/N 511407680-3 THE ENCODER TORQUE ARM, WHICH HOLDS THE ROTOR FIXED TO ONE SIDE OF JOINT, IS INTENTIONALLY MADE OF LIGHT SECTION ALUMINEUM, SO AS TO MINIMIZE ANY IMPARTED STRESS/FORCES INTO **OUTPUT.** UNRELIABLE AND NOT AND GTY-1 CAUSE(S): REPRESENTATIVE (1) TORQUE P/N 511400231-3 OF JOINT THE ENCODER ROTOR ASSEMBLY. POSTION. AUTO MODE WILL BE RESTRAINED CONSEQUENTLY CARE MUST BE TAKEN AT ALL TIMES TO AVOID INOPERATIVE. BY CABLE INTERFERENCE BETWEEN WIRE HARNESSES AND/OR THERMAL BLANKETS HARNESS OR CONSISTENCY WITH THE TORQUE ARM. THERMAL CHECK WILL **BLANKETS.** INITIATE AUTO BRAKES. IN AUTO ARN WILL STOP O RATE COMMAND TO ALL JOINTS. ENCODER CHECK.DIRECT, BACKUP AND SINGLE MODES OPERATIVE, LOSS OF LIMPING DURING END EFFECTOR CAPTURE. WORST CASE UNEXPECTED MOTION. **INCORRECT** POSTION DATA. AUTO BRAKES. REDUNDANT PATHS REMAINING **AUTOBRAKES**

RMS/MECH - 221

DATE: 24 JUL 91

CIL REV: 3

APPROVED BY:

HFUG

PREPARED BY:

PROJECT: SRMS ASS'Y NOMENCLATURE: MECHANICAL ARM

SYSTEM: MECHANICAL ARN SUBSYSTEM
ASS'Y P/N: 5114011565 SHEET: 2

FMEA FMEA HAME, DTY REF. REV. DRAWING I DESIGNATION	F. AND	FAILURE EFFECT ON END ITEM HDWR / FUNC. RATIONALE FOR ACCEPTANCE 2/1RA CRITICALITY SCREENS: A-FAIL, B-PASS, C-PASS
4040 3 OPTICAL POSITION ENCORR OTY-5 P/I 51140F68 AND OTY-P/II 51140023	HODE: ERRONEOUS ANGLE OUTPUT. CAUSE(S): (1) TORQUE ARM RESTRAINED BY CABLE HARMESS OR THERMAL BLANKETS. BLANKETS. BLANKETS. COLUMN	ACCEPTANCE TESTS INFORMATION TO COMPUTER IS UNRELIABLE AND HOT REPRESENTATIVE OF JOINT POSTION, AUTO MODE WILL BE INDERRATIVE. COMSISTERY CHECK WILL INITIATE AUTO BRAKES. IN AUTO ANN WILL STOP, O RATE COMPAND TO ARTE COMP

SUPERCEDING DATE: 24 NOV 86

ASS'Y NOMENCLATURE: HECHANICAL ARM SUBSYSTEM ASS'Y PURE 5114011585 SHEET: 3

REF.	HEA NAME OTY EV. DRAWING RE DESIGNATION	F. AND	FAILURE EFFECT ON END ITEM	HDWR / FUNC. RATIONALE FOR ACCEPTANCE 2/1RA CRITICALITY SCREENS: A-FALL H-PASS C-PASS
4040	DESIGNATION ENCODER 01Y-5 P/N 51140F680- AND 01Y-1 P/M 511400231-	MCOE: ERRONECUS ANGLE OUTPUT. 3 CAUSE(S): (1) TORQUE	THE POSTION INFORMATION TO COMPUTER IS UNRELIABLE AND NOT REPRESENTATIVE OF JOINT POSTION.AUTO MODE WILL INOTENTY CHECK WILL INITIATE AUTO BRAKES. IN AUTO ARM WILL STOP,O RATE COMMAND TO ALL JOINTS.ENCODER CHECK.DIRECT, BACKUP AND SINGLE MODES OPERATIVE. LOSS OF LINDING DURING END EFFECTOR CAPTURE. WORST CASE UNEXPECTED MOTION. INCORRECT POSTION DATA. AUTO BRAKES. REDUNDANT PATHS REMAINING AUTOBRAKES	

RMS/MECH - 223

PROJECT: SRMS ASS'Y NOMENCLATURE: <u>MECHANICAL ARM</u> SYSTEM: MECHANICAL ARM SUBSYSTEM
ASS'Y P/N: 51140J1565 SHEET: 4

HDWR / FUNC. 2/1RA CRITICALITY RATIONALE FOR ACCEPTANCE FAILURE HODE FATTURE EFFECT NAME, GTY, & DRAWING REF. FMEA FHEA AND REV. REF. END ITEM SCREENS: A-FAIL, B-PASS, C-PASS CAUSE DESIGNATION THE POSTION INFORMATION TO COMPUTER IS OPTICAL POSITION MODE: ERRONEOUS POINT) 3 4040 ANGLE OUTPUT. ENCODER QTY-5 P/N 51140#680-3 AND QTY-1 UNREL JABLE AND NOT CAUSE(S): REPRESENTATIVE (1) TORQUE OF JOINT P/N 511400231-3 POSTION AUTO RESTRAINED MODE WILL BE INOPERATIVE. BY CABLE HARNESS OR CONSISTENCY CHECK WILL INITIATE AUTO THERMAL BLANKETS. BRAKES. IN AUTO ARM WILL STOP O RATE COMMAND TO ALL JOINTS.ENCODER
CHECK.DIRECT,
BACKUP AND
SINGLE MODES
OPERATIVE. LOSS OF LIMPING DURING END EFFECTOR CAPTURE. WORST CASE UNEXPECTED MOTION. INCORRECT POSTION DATA. AUTO BRAKES. REDUNDANT PATHS REMAINING **AUTOBRAKES**

PREPARED BY:

MEMG

SUPERCEDING DATE: 24 NOV 86

RMS/MECH - 224

DATE: 24 JUL 91

CIL REV: 3

PROJECT: SRMS ASS'Y NOMENCLATURE: MECHANICAL ARM SYSTEM: MECHANICAL ARM SUBSYSTEM
ASS'Y P/R: 51140J1565 SHEET: 5

FMEA REF.	FMEA REV.	HAME QTY, & Drawing Ref. Designation	FAILURE MODE AND CAUSE	FAILURE EFFECT ON END ITEM	HDWR / FUNC. RATIONALE FOR ACCEPTANCE 2/1RA CRITICALITY SCREEMS: A-FAIL, B-PASS, C-PASS
4040	3	OPTICAL POSITION ENCODER OTY-5 P/N 51140F680-3 AND OTY-1 P/N 511400231-3	MODE: ERROMEGUS ANGLE OUTPUT. CAUSE(S): (1) TOROUE ARM RESTRAIMED BY CABLE NARMESS OR THERMAL BLANKETS.	THE POSTIOM INFORMATION TO COMPUTER IS UNRELIABLE AND NOT REPRESENTATIVE OF JOINT POSTION AUTO MODE WILL BE INOPERATIVE. CONSISTENCY CHECK WILL INITIATE AUTO BRAKES. IN AUTO ARM MILL STOP, O RATE COMMAND TO ALL JOINTS.ENCODER CHECK, DIRECT, BACKUP AND SINGLE MODES OPERATIVE. LOSS OF LIMPING DURING END EFFECTOR CAPTURE. WORST CASE UNEXPECTED MOTION. INCORRECT POSTION DATA. AUTO BRAKES. REDUNDANT PATHS REMAINING AUTOBRAKES	THE FOLLOWING FAILURE ANALYSIS REPORT(S) ARE RELEVANT: FAR 2013: S/M 203 OCT 78 DESCRIPTION FAILED FUNCTIONAL FOLLOWING T/V DUE TO MARPING OF HOUSING, HOUSINGS WERE MARPED AFTER PRODUCTION, WERE REMORKED BUT NOT STRESSED RELIEVED. T/V STRESS RELIEVED CORRECTIVE ACTION REMORKED HOUSINGS AVAILABLE, ENCODERS S/M 202, 204, 205 DELIVERED WITH FAULT. NO AMAMOLIES MOTED IN SRU TEST. FAR 2056: S/M 202 MAR 79 DESCRIPTION RUN-OUT OUT OF SPEC AFTER ENVIRONMENTAL TEST. CORRECTIVE ACTION UNIT REMORKED TO DRAWING. REFER TO DRAWING. REFER TO FAR 2013 FAR 2362: S/M 302 JUN 63 DESCRIPTION ANGLE OF TRAVEL O.O.S CABLE INTERFERRED WITH ENCODER TOROUGE ARM CORRECTIVE ACTION RELAYED CABLE

RMS/MECH - 225

MF WG

PREPARED BY:

DATE: 24 JUL 91

CIL REV: 3

SUPERCEDING DATE: 24 NOV 86